

Supervised Pattern Set Mining

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Overview

Differences/Similarities to Unsupervised PSM

- Supervised measures

Partitioning the data

Four ways of going about it

- CBA
- DTM
- fCork
- ReMine

Related issues

What's different?

Different data sets

- ✦ i.e. different points in time, locations



Data split into subsets

- ✦ different classes
- ✦ subgroups w.r.t. target attribute

Tasks related to target

- ✦ find contrasting patterns
- ✦ class prediction
- ✦ describe subgroups for further offline analysis



Unsupervised methods
may be able to help as well

(Pseudo-)Notation

Not only itemsets

- change matching-relation

$$X \subseteq t \rightarrow P \preceq t$$

$$\text{cov}(P) = \{t \mid P \preceq t\}$$

We don't care about
pattern language

“Naming” the subsets

$$\text{class}_1 = db \cap \{\bullet\}$$

$$\text{class}_2 = db \cap \{\bullet\}$$

Supervised Measures

Accuracy, Confidence

- Conditional probability



$$acc(P) = \frac{\max\{sup_{class_1}(P), sup_{class_2}(P)\}}{sup_{db}(P)}$$

No consideration of coverage

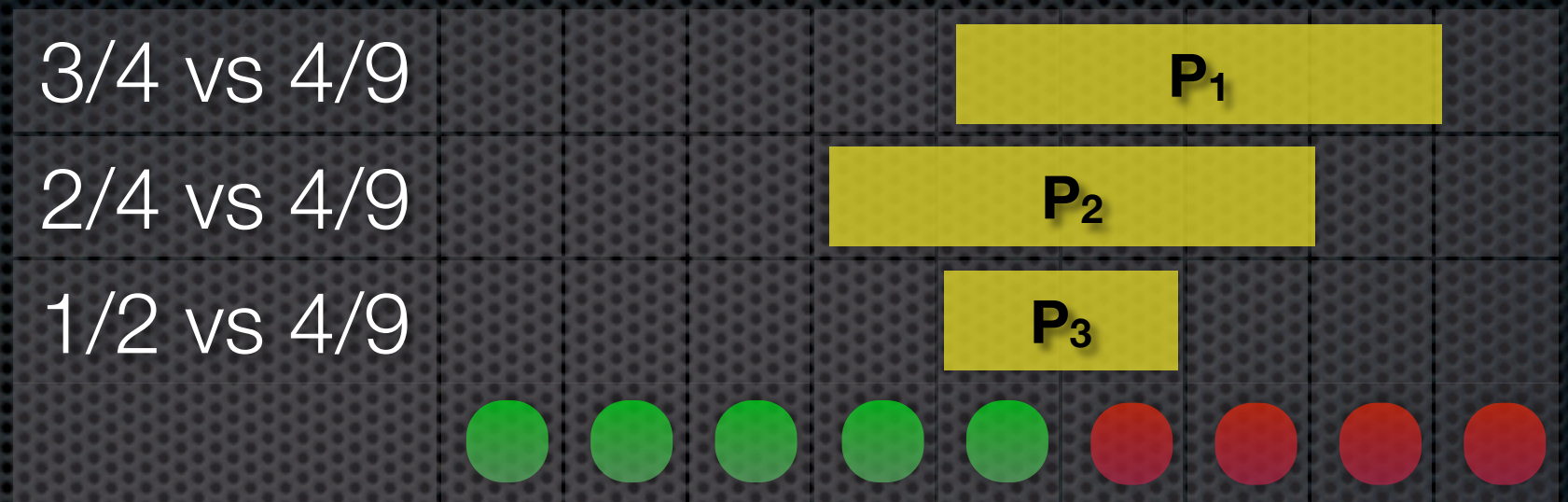
- Augmentation needed
- Upper bound **1**

Supervised Measures

0.991

Correlation

- compare conditional probability to overall probability



Information Gain

- related to entropy

$$\boxed{ent_{class}(db)} = - \sum_{i=1}^2 \frac{|class_i|}{|db|} \log \frac{|class_i|}{|db|}$$

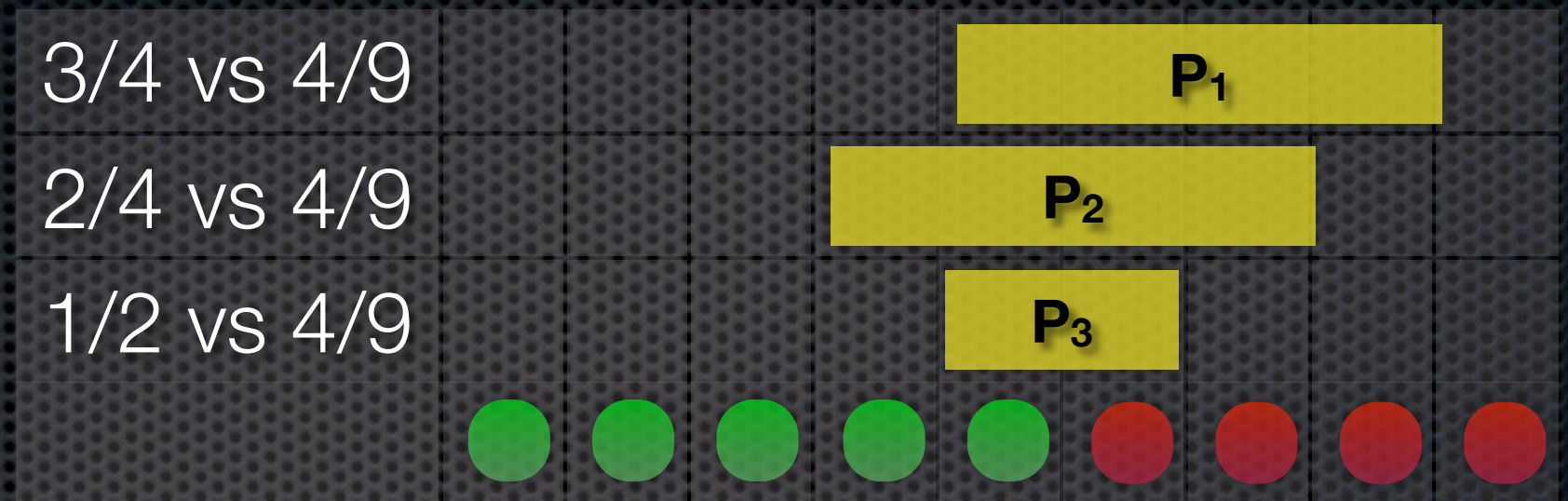
$$IG(P) = ent_c(db) - \frac{|cov(P)|}{|db|} ent_c(cov(P)) - \frac{|db \setminus cov(P)|}{|db|} ent_c(db \setminus cov(P))$$

Supervised Measures

0.991

Correlation

- compare conditional probability to overall probability



Information Gain

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$$ent_{class}(db) = - \sum_{i=1}^2 \frac{|class_i|}{|db|} \log \frac{|class_i|}{|db|}$$

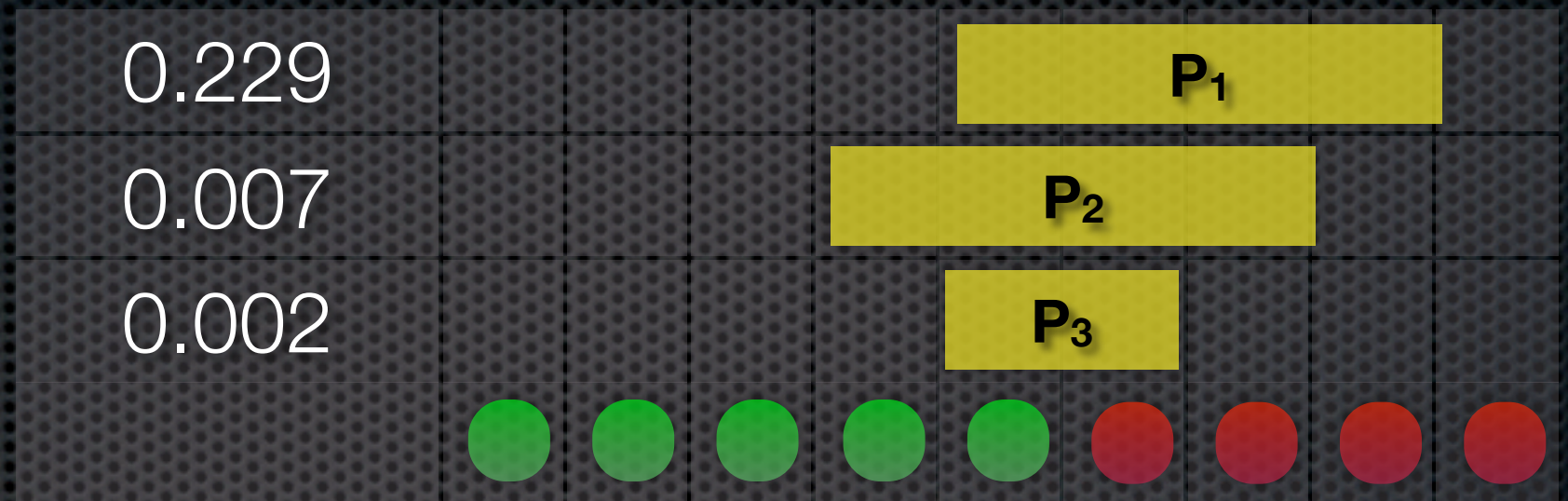
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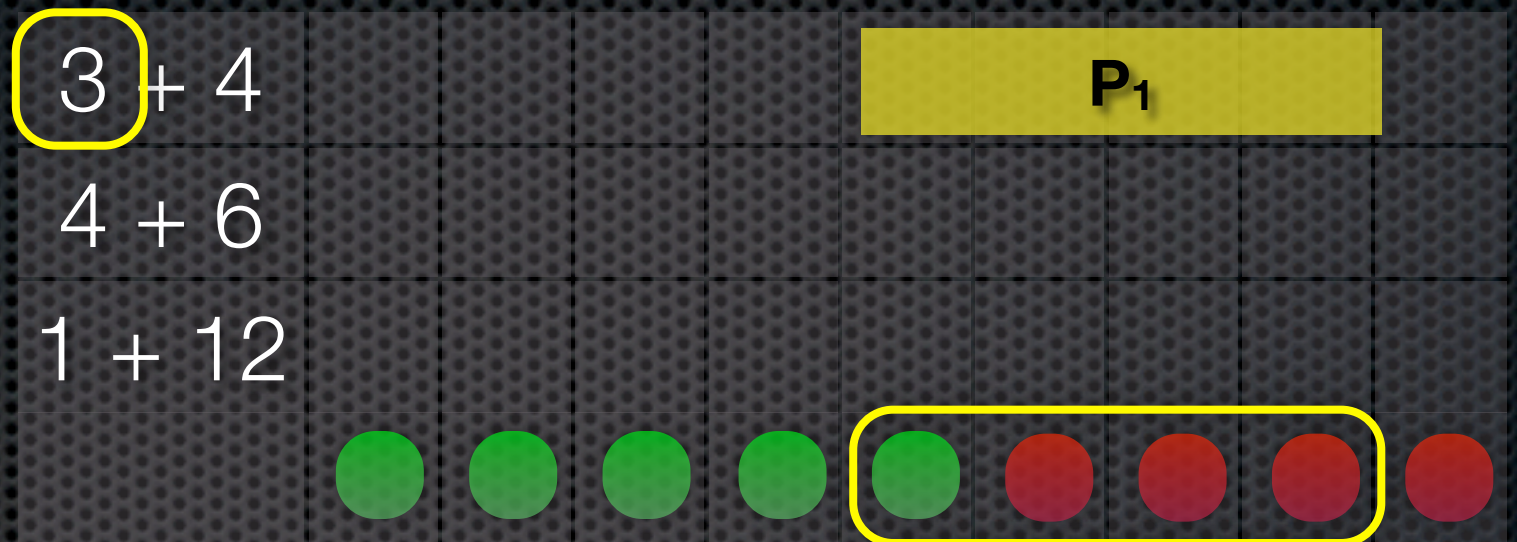
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Upper-boundable

Supervised Measures

Correspondence

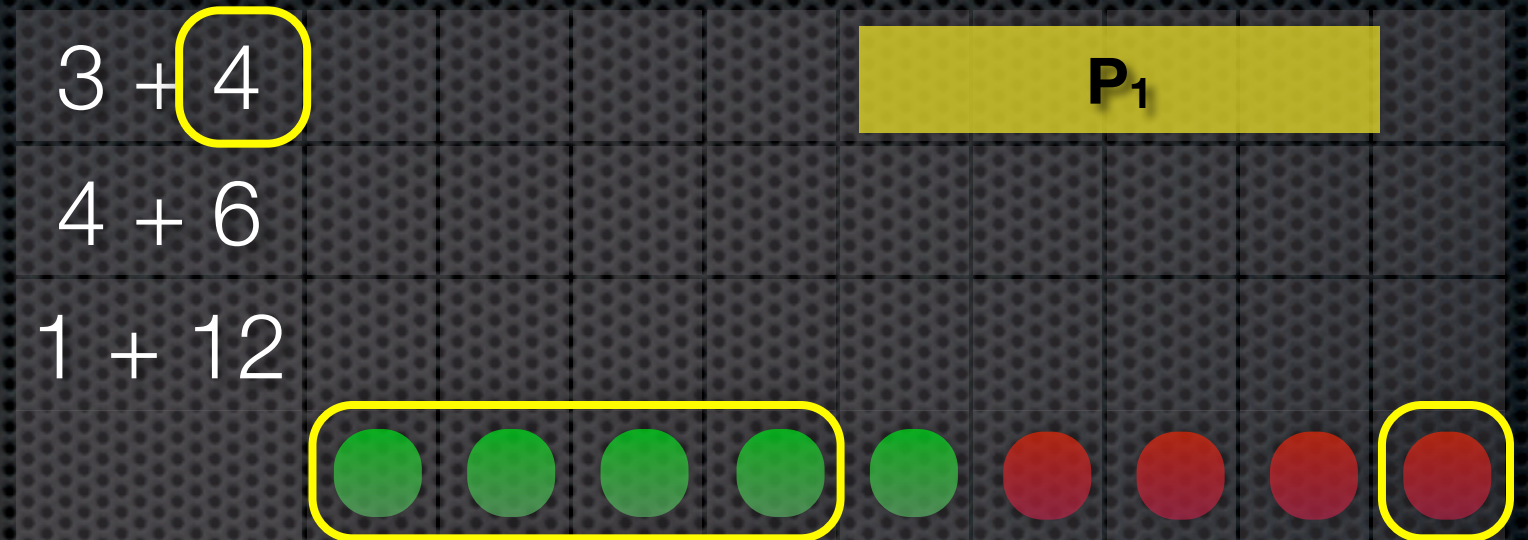
- Count number pairs from different sets



Supervised Measures

Correspondence

- ✖ Count number pairs from different sets

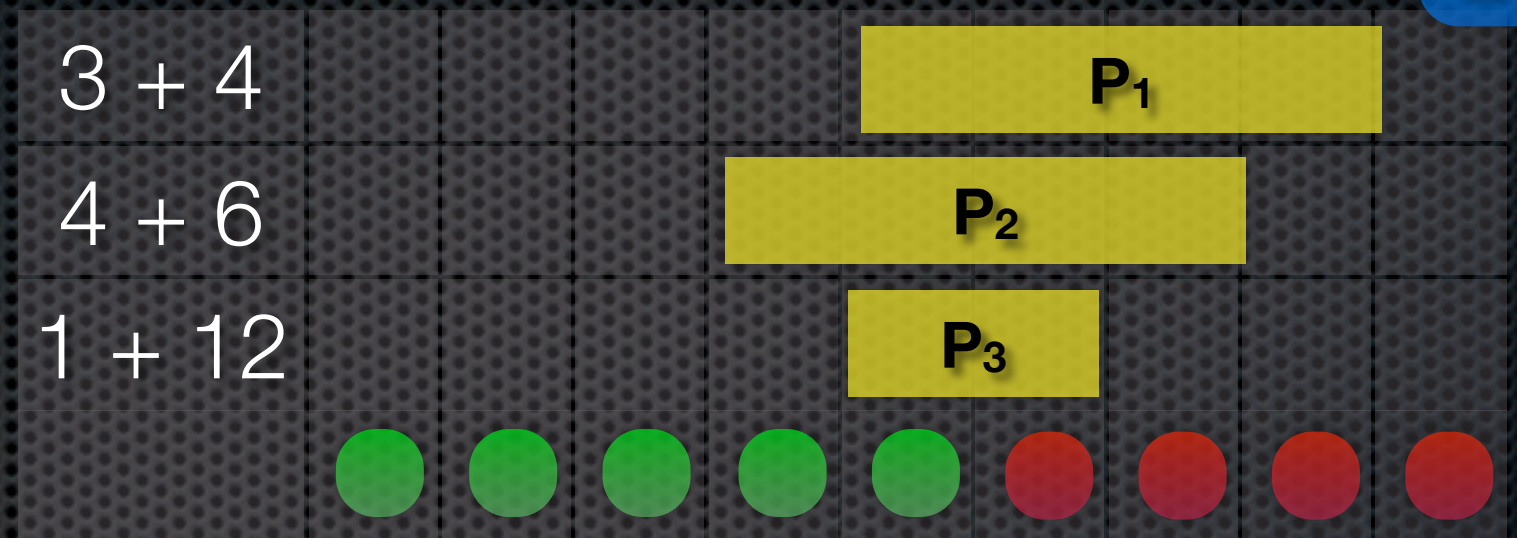


Supervised Measures

20

Correspondence

- Count number pairs from different sets



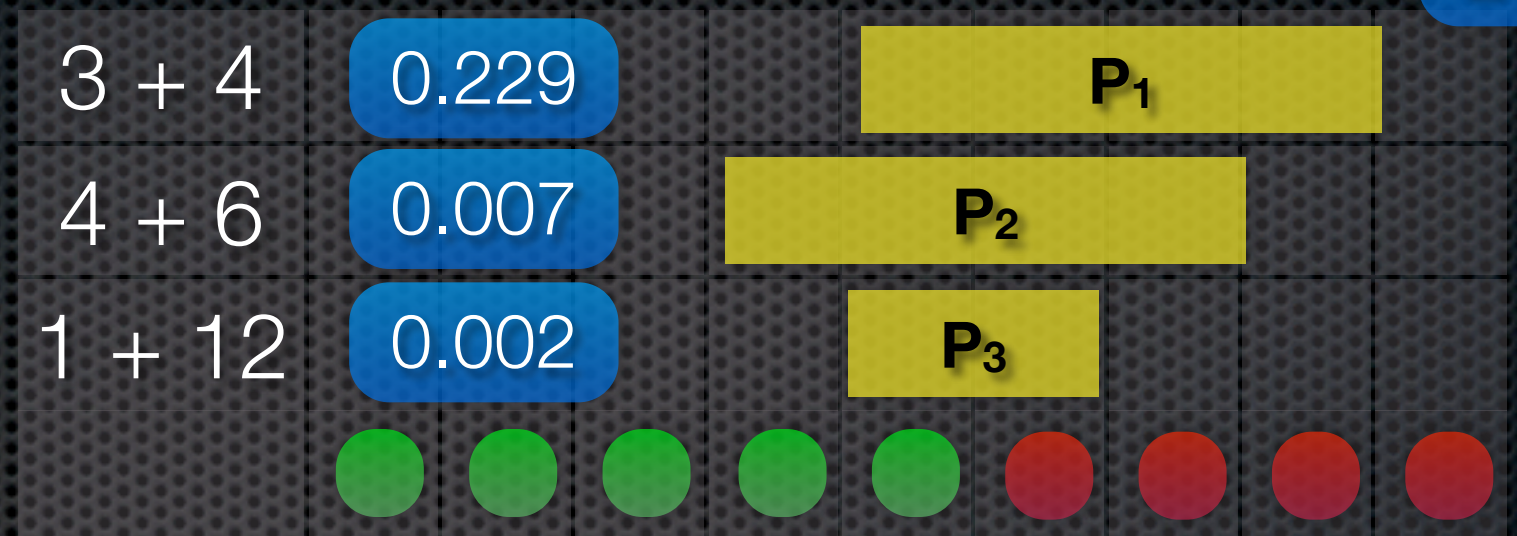
$$\text{corr}(P) = \text{sup}_{c_1}(P) \cdot \text{sup}_{c_2}(P) + (|c_1| - \text{sup}_{c_1}(P)) \cdot (|c_2| - \text{sup}_{c_2}(P))$$

Supervised Measures

20

Correspondence

- Count number pairs from different sets



$$\text{corr}(P) = \text{sup}_{c_1}(P) \cdot \text{sup}_{c_2}(P) + (|c_1| - \text{sup}_{c_1}(P)) \cdot (|c_2| - \text{sup}_{c_2}(P))$$

Upper-boundable
Sub-modular

What's the same?

We want few patterns:

- Alleviating the effect of the curse of dimensionality
- Enhancing generalization capability
- Speeding up learning process
- Improving model interpretability (or description analysis)

We want high-quality patterns

- Predictive or typical

We want little redundancy

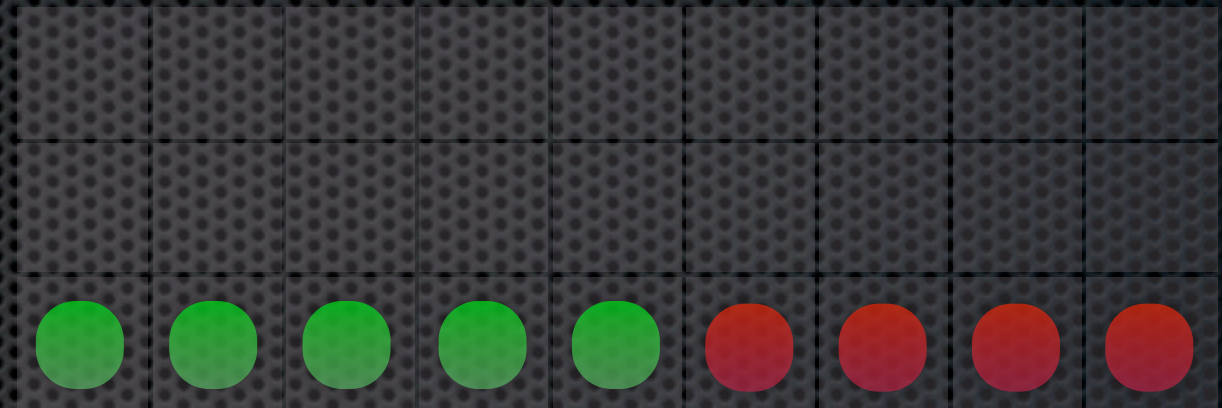
- Discovering same subgroup over and over helps no one

Combination with unsupervised
measures possible

Patterns as splits

Imposes new
subsets

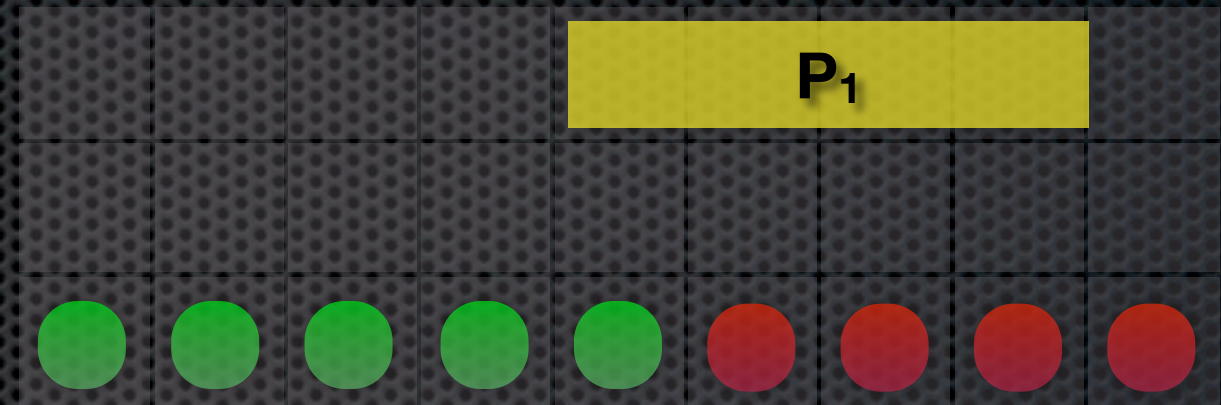
- ✦ Pattern absence/
presence becomes new
property of data point



Patterns as splits

Imposes new subsets

- ✱ Pattern absence/
presence becomes new
property of data point



Patterns as splits

Relate pattern split to original split

Imposes new subsets

- ✱ Pattern absence/
presence becomes new
property of data point

Diagram illustrating a 1D lattice with two rows: Uncovered and Covered. The Covered row shows a yellow bar labeled P_1 covering the first three cells. The bottom row contains 10 circles: the first three are green, and the next seven are red.

Patterns as splits

Relate pattern split to original split

Imposes new subsets

- ✦ Pattern absence/
presence becomes new
property of data point

Diagram illustrating a 1D lattice with 9 sites. The lattice is divided into two regions: 'Uncovered' (left) and 'Covered' (right). The 'Covered' region is highlighted in yellow and labeled P_1 . The bottom row shows the state of the lattice: green circles represent uncovered sites, and red circles represent covered sites. The first 6 sites are uncovered (green), and the last 3 sites are covered (red).

| | | | | | | | | | |
|-------|---|---|---|---|---|---|---|---|---|
| P_1 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
|-------|---|---|---|---|---|---|---|---|---|

Patterns as splits

Relate pattern split to original split

Imposes new subsets

- ✦ Pattern absence/
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| | | | | | | | | | |
|-------|---|---|---|---|---|---|---|---|---|
| P_2 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 0 |
|-------|---|---|---|---|---|---|---|---|---|


Patterns as splits

Relate pattern split to original split

Imposes new subsets

- ✱ Pattern absence/
presence becomes new
property of data point

Diagram illustrating a 1D lattice with 9 sites. The lattice is divided into two regions: Uncovered (left) and Covered (right). The Covered region is highlighted in yellow and labeled P_1 . The lattice is populated with particles: Green circles (representing \uparrow) are located at sites 1, 2, 3, 6, and 7. Red circles (representing \downarrow) are located at sites 4, 5, 8, and 9.

| | | | | | | | | | |
|-------|---|---|---|---|---|---|---|---|---|
| P_3 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 |
| |  |  |  |  |  |  |  |  |  |

Pattern sets as partitions

More than one pattern








⇒ additional presence

indicators

⇒ identification of data

points with binary vectors

⇒ more numerous splits

| | | | | | | | | | |
|-------|---|---|---|---|---|---|---|---|---|
| P_1 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| P_2 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 0 |
| P_3 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 |
| |  |  |  |  |  |  |  |  |  |

Pattern sets as partitions

More than one pattern










⇒ additional presence

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| P_1 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| P_2 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 0 |
| P_3 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 |
| |  |  |  |  |  |  |  |  |  |

Pattern sets as partitions

More than one pattern










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| | | | | | | | | | |
|-------|---|---|---|---|---|---|---|---|---|
| P_1 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| P_2 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 | 0 |
| P_3 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 |
| |  |  |  |  |  |  |  |  |  |

| | | | | | | | | |
|---|---|---|---|---|---|---|---|---|
| | | | | | P_1 | | | |
| | | | | | | | | |
| | | | | | | | | |
|  |  |  |  |  |  |  |  |  |

Pattern sets as partitions

More than one pattern










⇒ additional presence

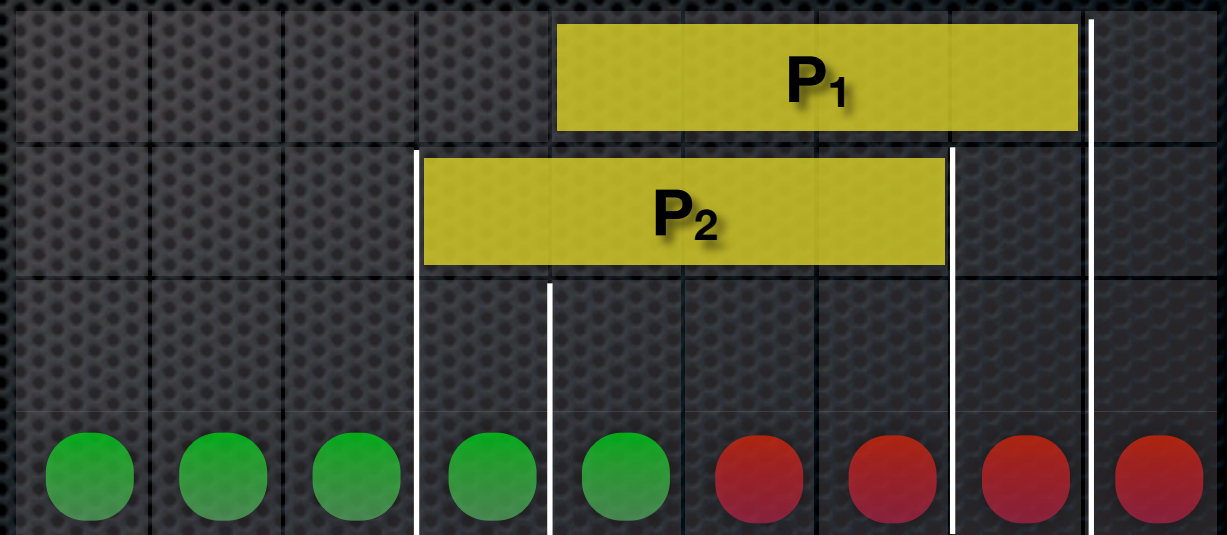
indicators

⇒ identification of data

points with binary vectors

⇒ more numerous splits

| | | | | | | | | | |
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| |  |  |  |  |  |  |  |  |  |



Pattern sets as partitions

More than one pattern










⇒ additional presence

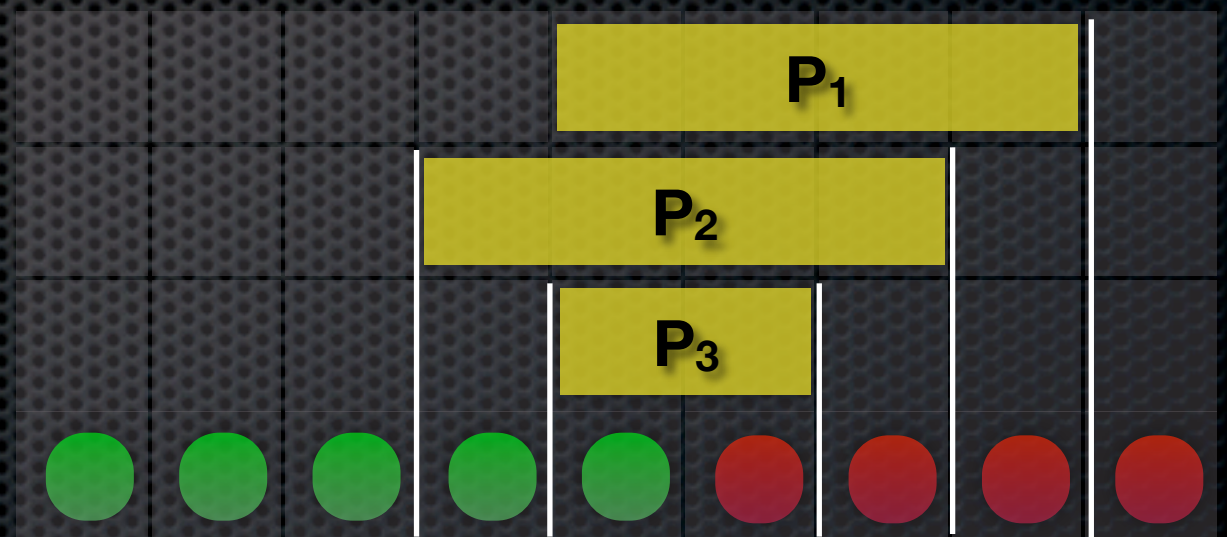
indicators

⇒ identification of data

points with binary vectors

⇒ more numerous splits

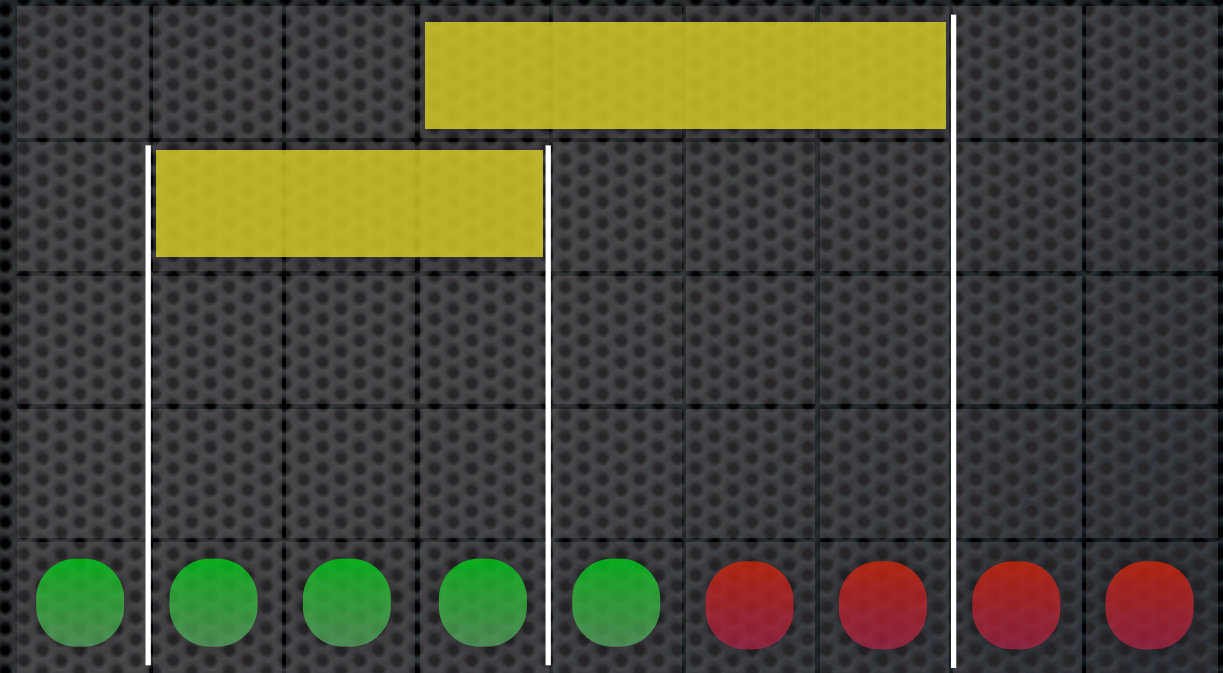
| | | | | | | | | | |
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| P_3 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 |
| |  |  |  |  |  |  |  |  |  |



Partitions as Redundancy-Measure

Are new splits created?

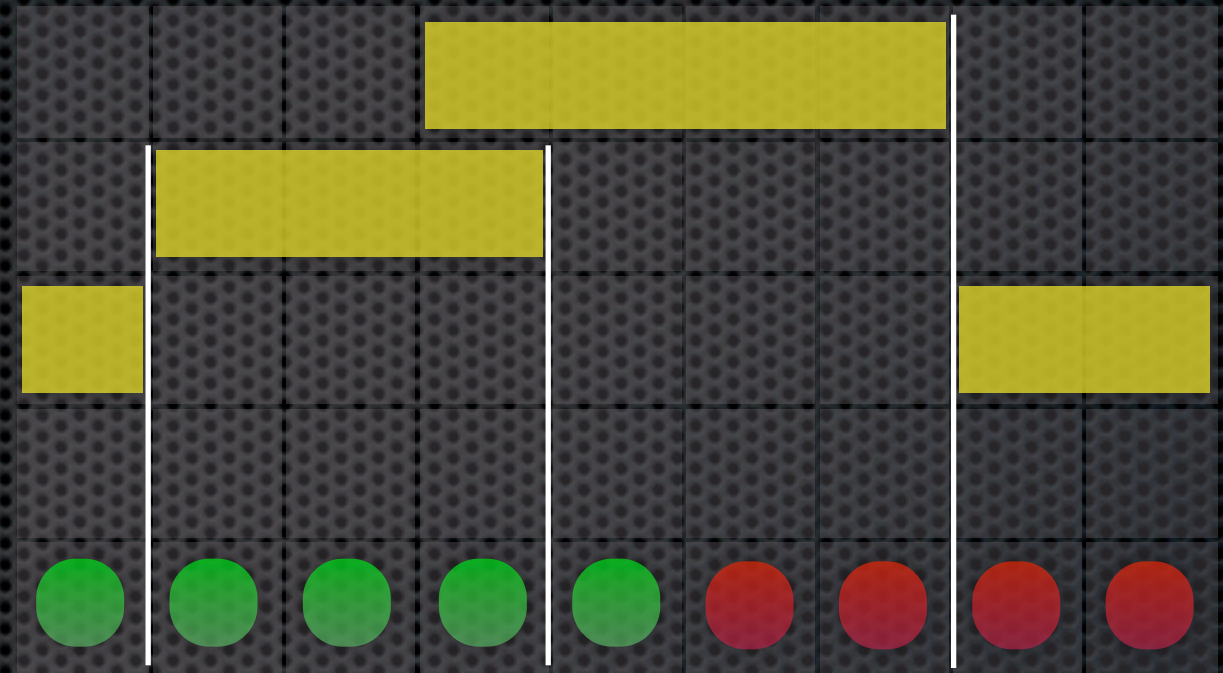
- If not, pattern redundant



Partitions as Redundancy-Measure

Are new splits created?

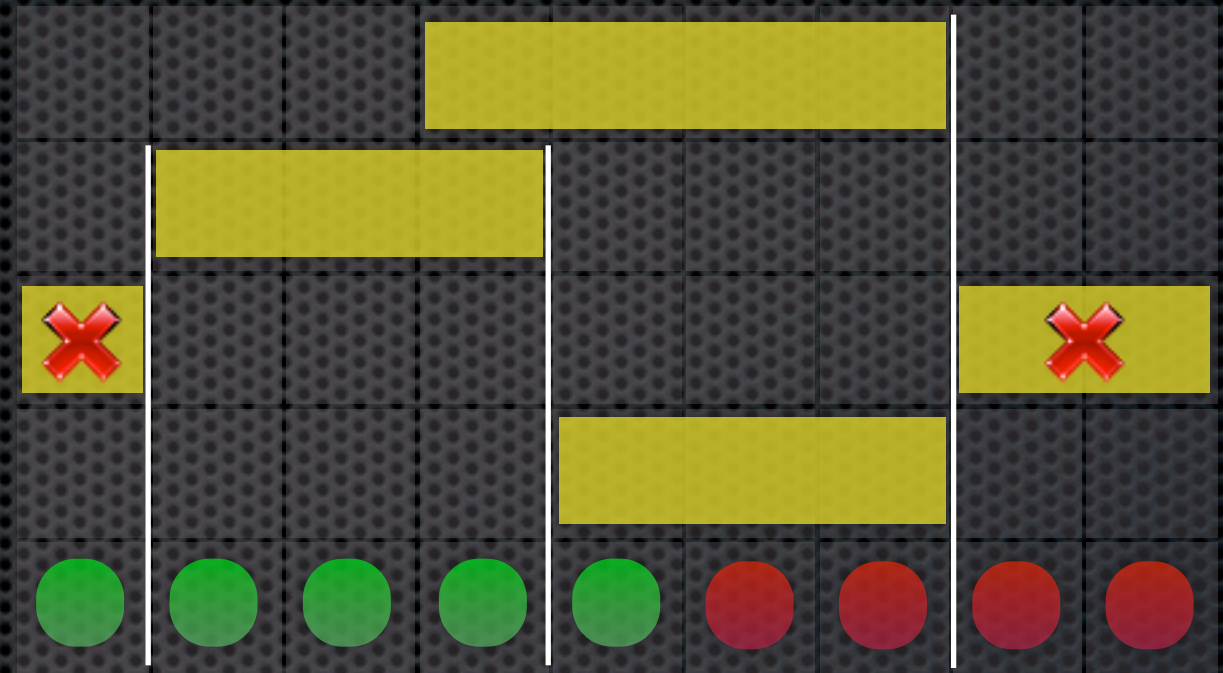
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Partitions as Redundancy-Measure

Are new splits created?

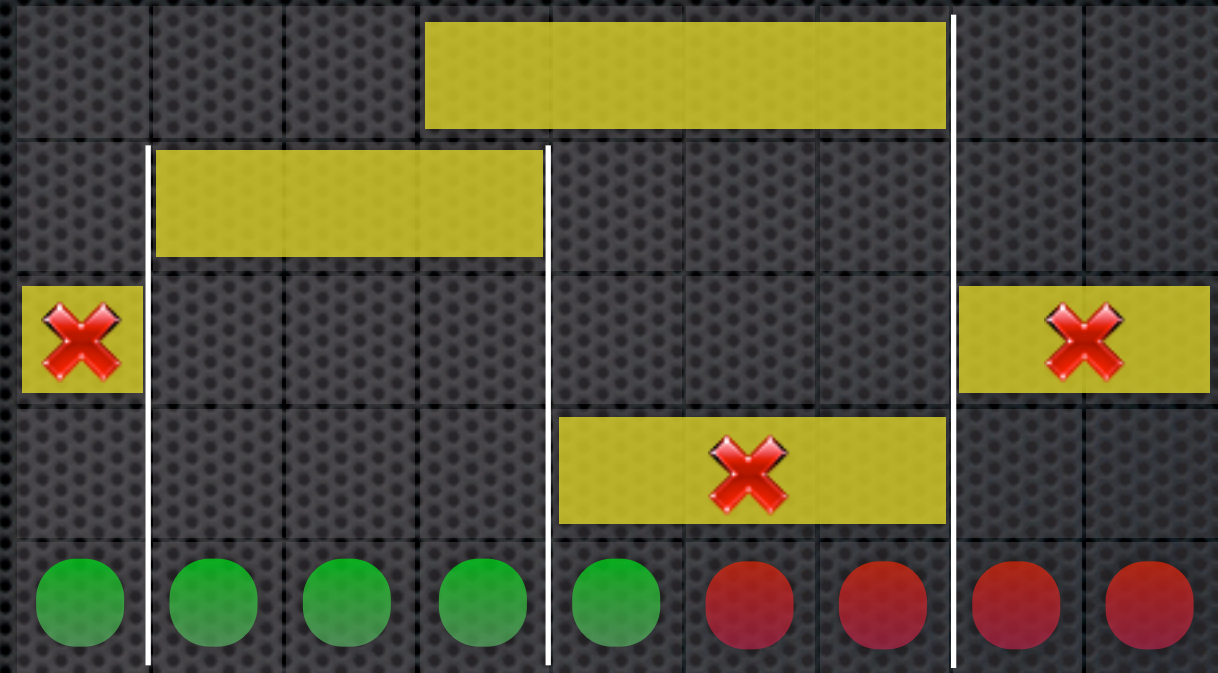
- If not, pattern redundant



Partitions as Redundancy-Measure

Are new splits created?

- If not, pattern redundant



Putting it together

Goal: “optimal” pattern set for given task

- Globally optimal mostly impossible
- Also, there’s over-fitting

Locally optimize supervised measure

- For individual pattern

Refine partition

- To avoid redundancy, encourage diversity

Choose next pattern

Accuracy
Correlation
Correspondences

Post-Processing (CBA)

Measure: Confidence

Optimization: Locally

Partition refinement: Globally, implicit

Fixed order on patterns

Sequentially processed

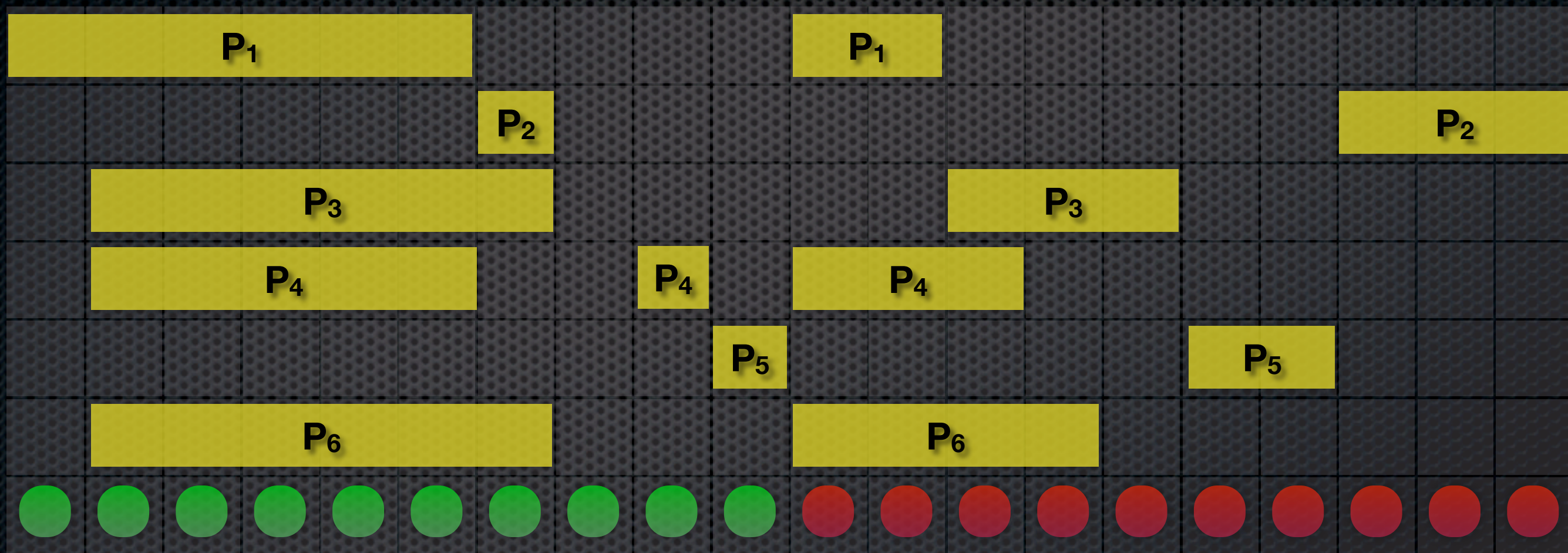
Only consider **uncovered** data points

Patterns **have to** classify correctly

How does it look?

Ordered by descending confidence

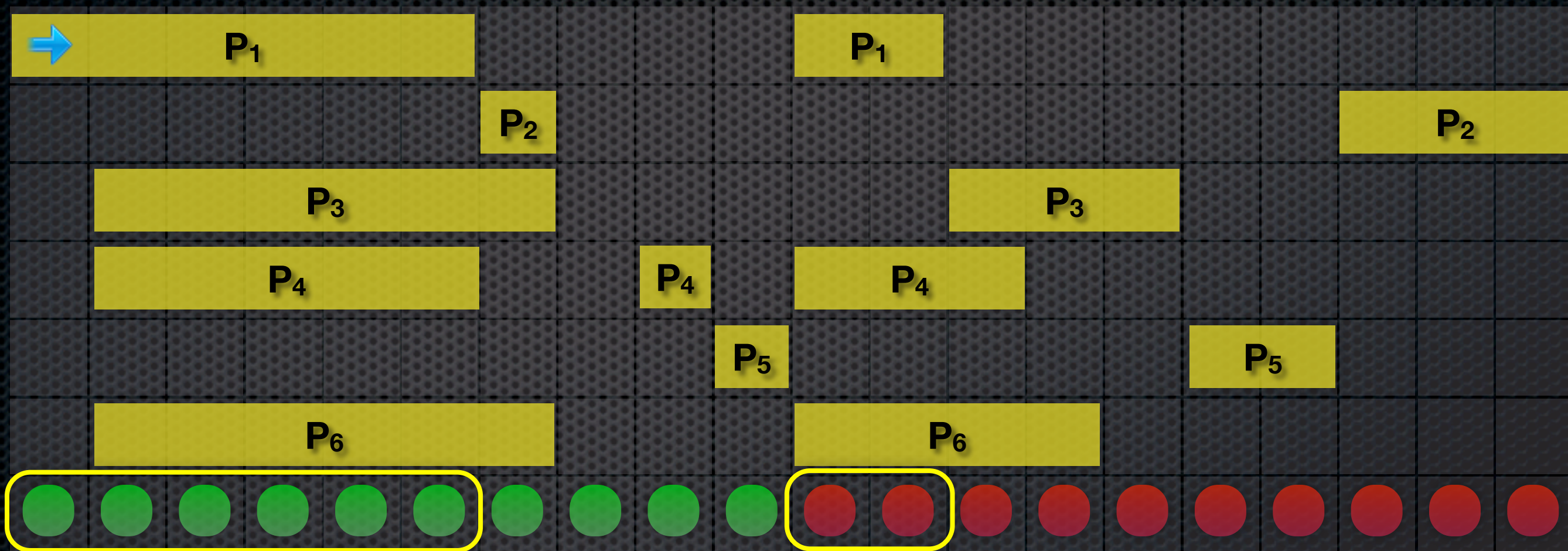
- Same confidence \rightarrow by descending support



How does it look?

Ordered by descending confidence

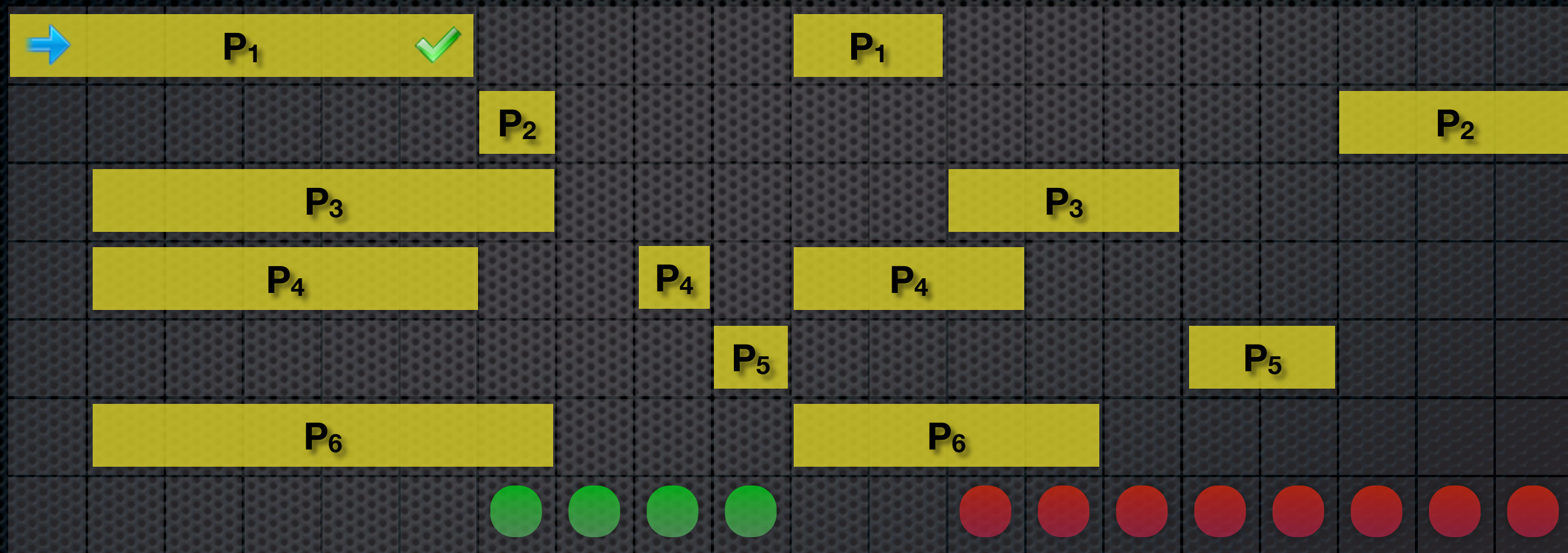
- Same confidence → by descending support



How does it look?

Ordered by descending confidence

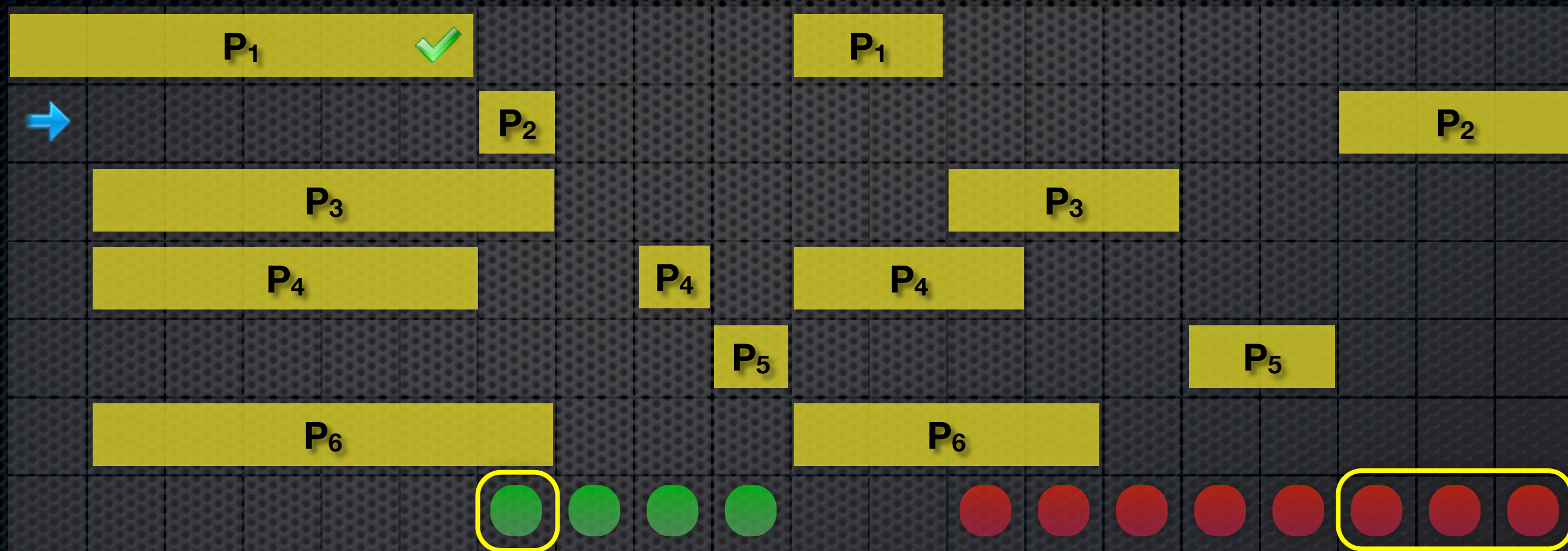
- Same confidence → by descending support



How does it look?

Ordered by descending confidence

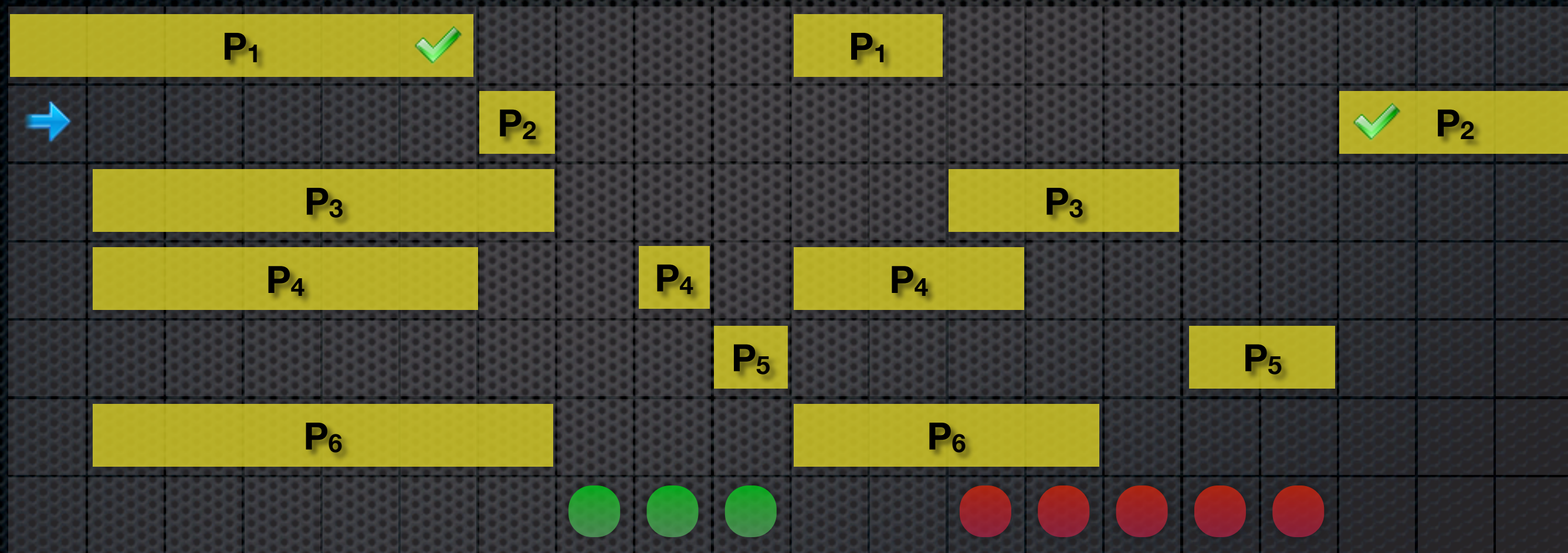
- Same confidence → by descending support



How does it look?

Ordered by descending confidence

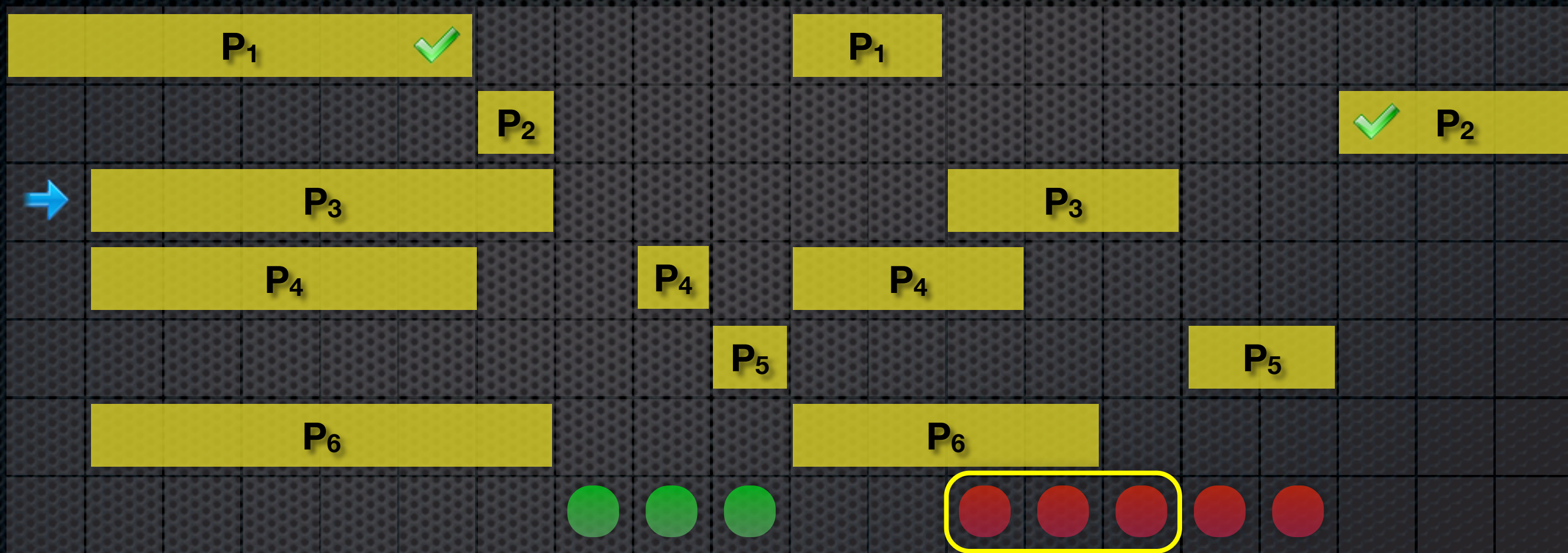
- Same confidence → by descending support



How does it look?

Ordered by descending confidence

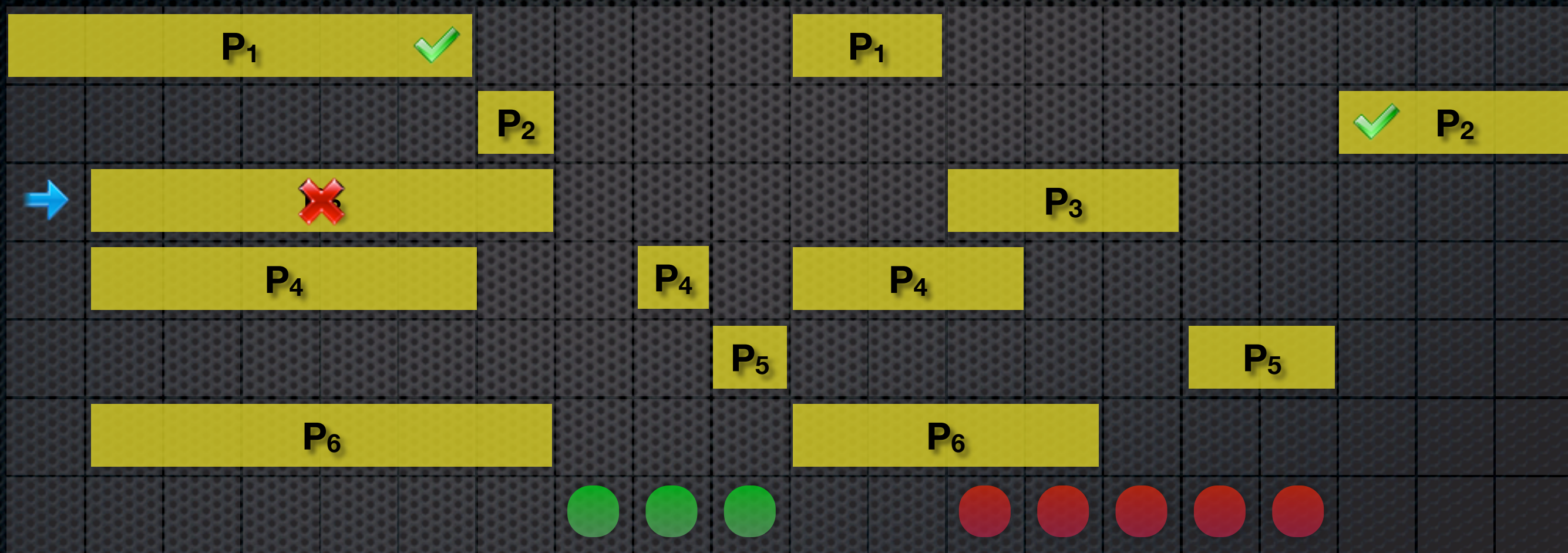
- Same confidence → by descending support



How does it look?

Ordered by descending confidence

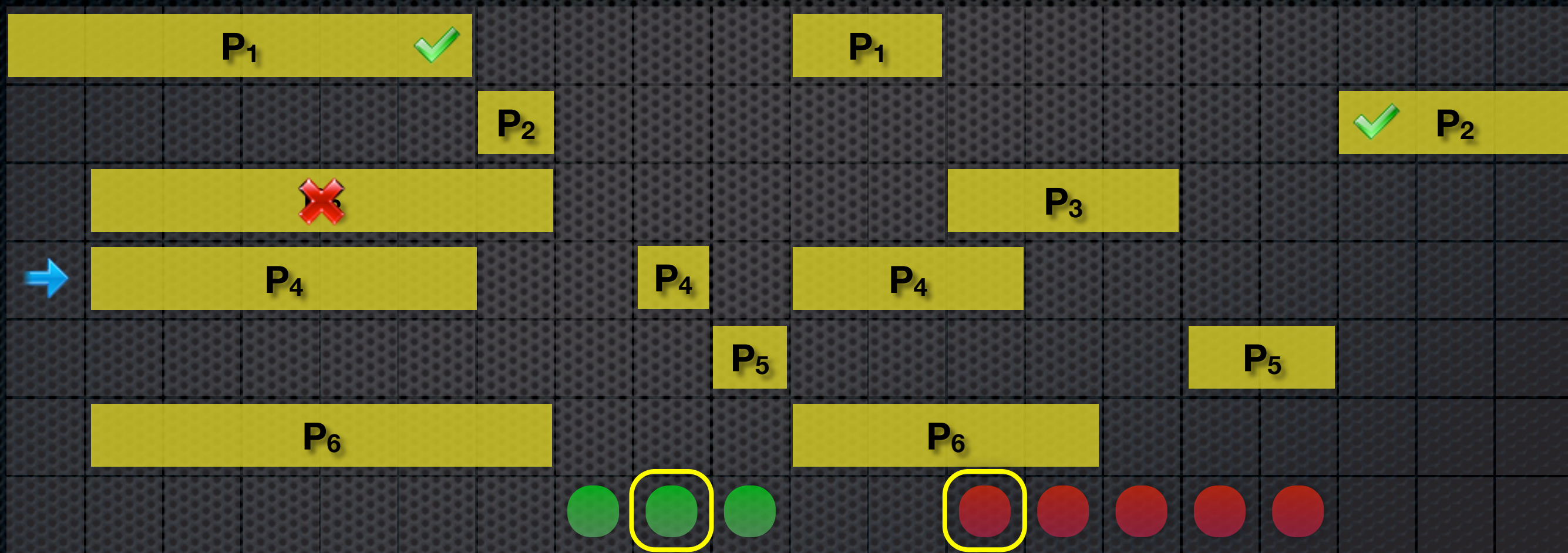
- Same confidence → by descending support



How does it look?

Ordered by descending confidence

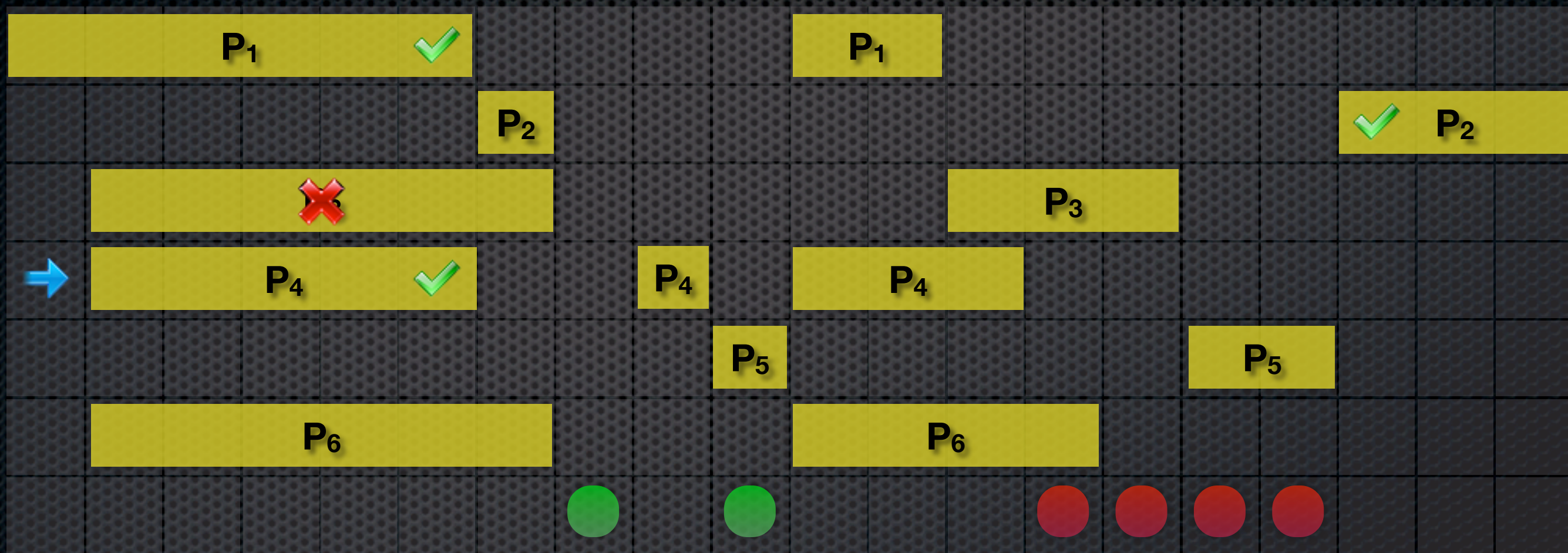
- Same confidence → by descending support



How does it look?

Ordered by descending confidence

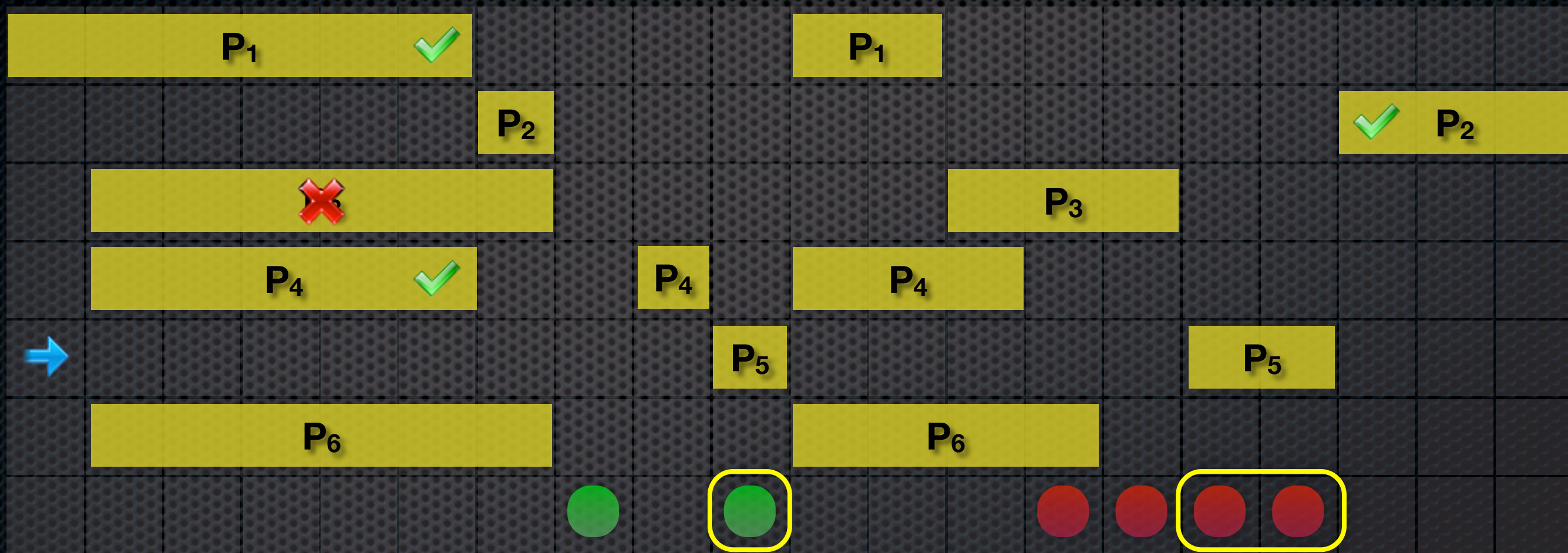
- Same confidence → by descending support



How does it look?

Ordered by descending confidence

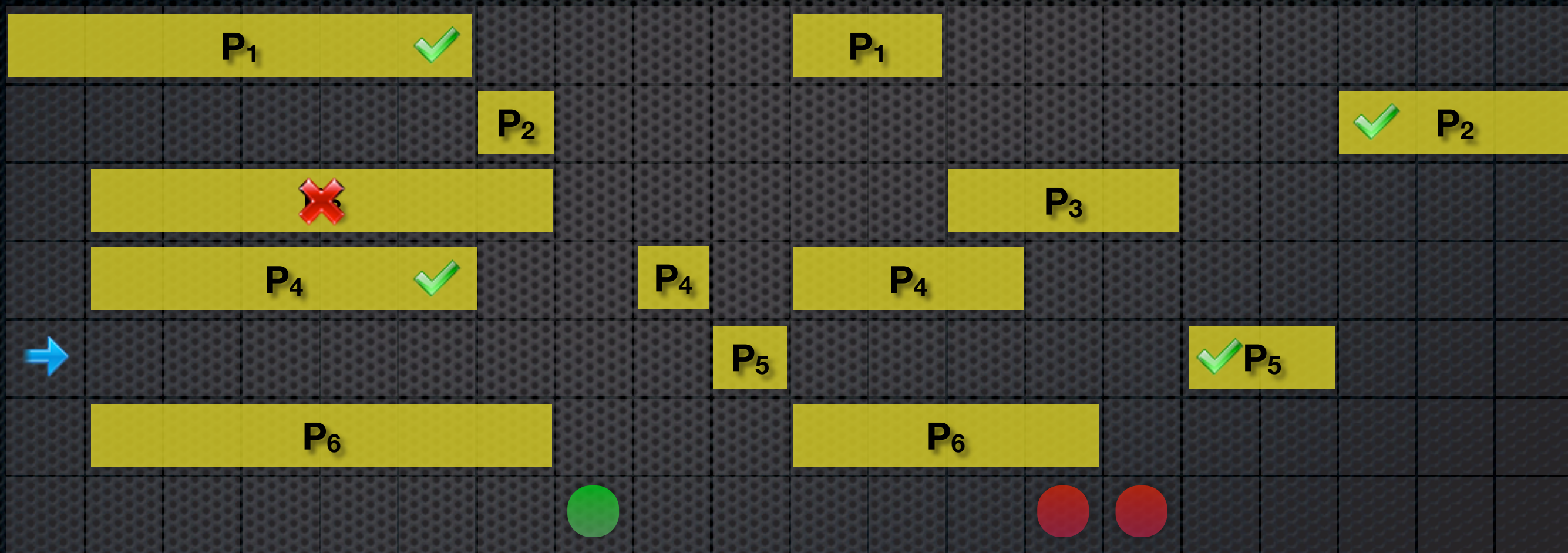
- Same confidence → by descending support



How does it look?

Ordered by descending confidence

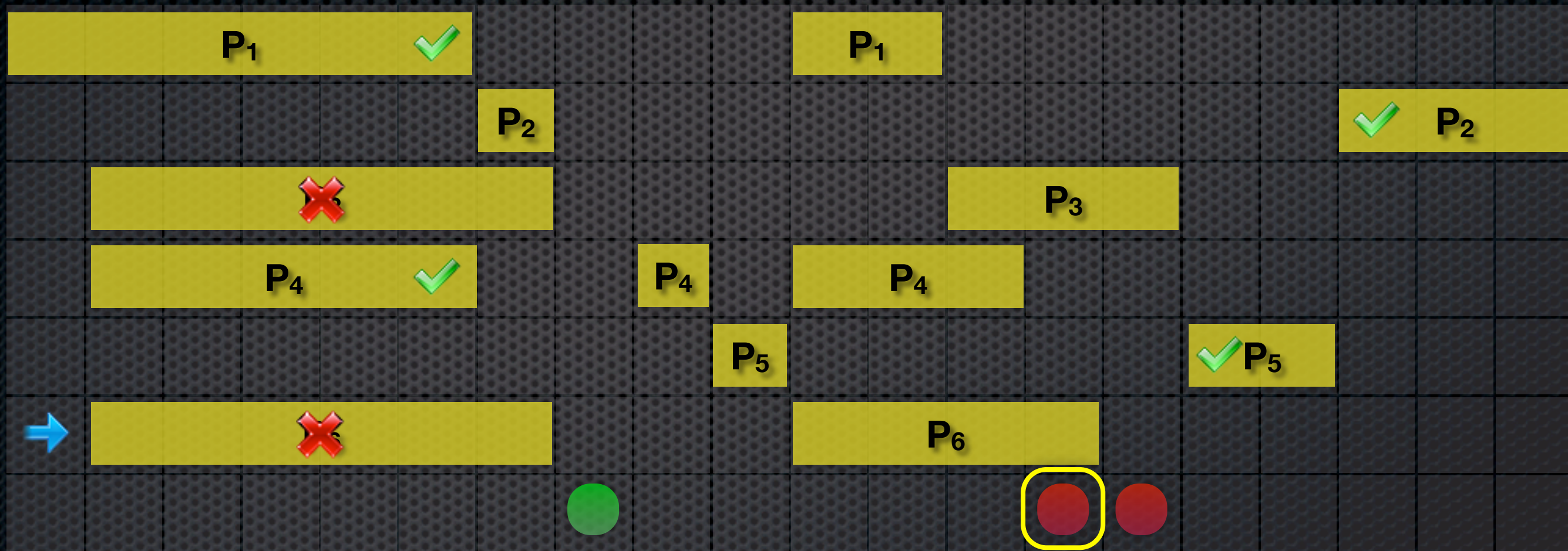
- Same confidence → by descending support



How does it look?

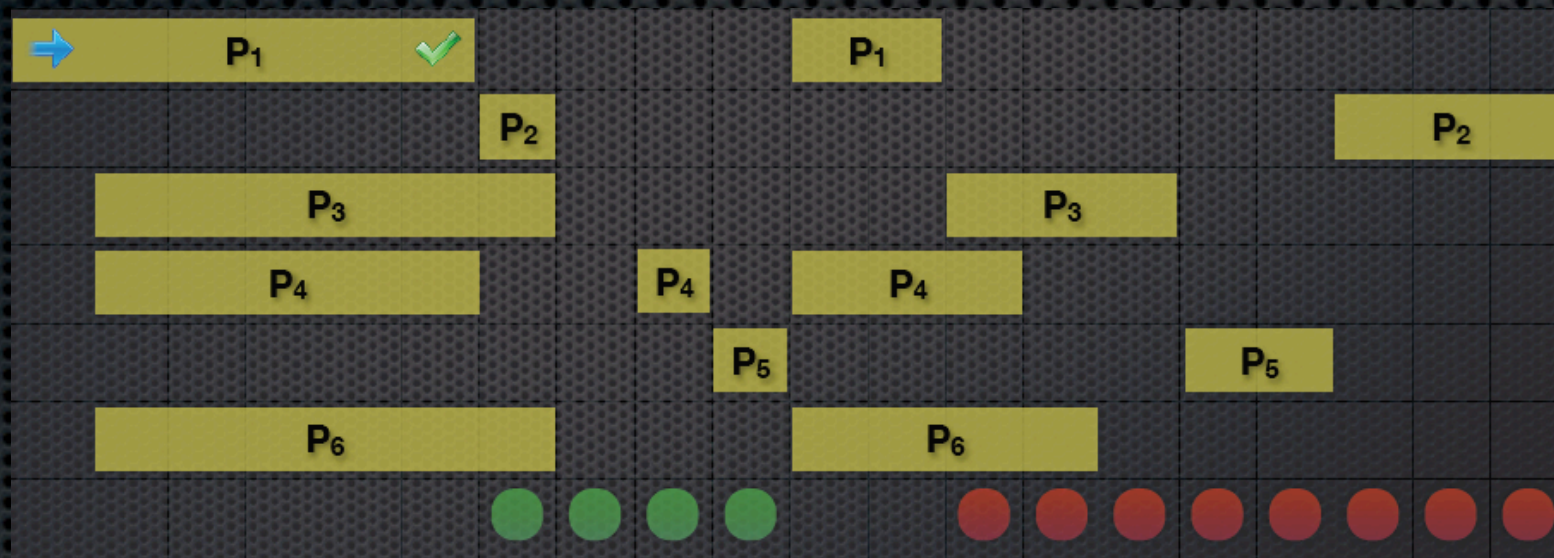
Ordered by descending confidence

- Same confidence → by descending support



(Potential) Problems

Post-processing can miss out on interesting patterns



Fixed order doesn't take changes in partition into account



Remind you of something?

Well-known Machine Learning technique: Sequential covering

- ✦ Used to learn classification rules
- ✦ Find very accurate rule
- ✦ Remove covered examples
- ✦ Learn on the remains

Iterative Mining!

1. Mine “optimal” pattern
2. Refine partition
3. Re-iterate

DTM - Decision Tree Mining

Measure: Information Gain (as in decision trees)

Optimization: Locally

Split: Locally (as in decision trees), explicit

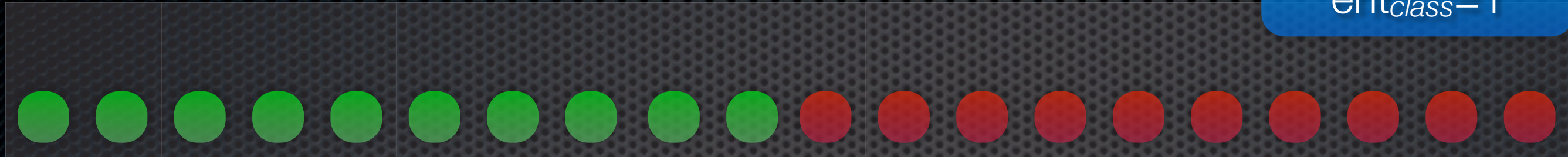
Mine pattern maximizing InfoGain

Use pattern to split data on which it was mined in 2 subsets

Reiterate on subsets

How does it look?

ent_{class}=1



How does it look?

IG = 0.2781

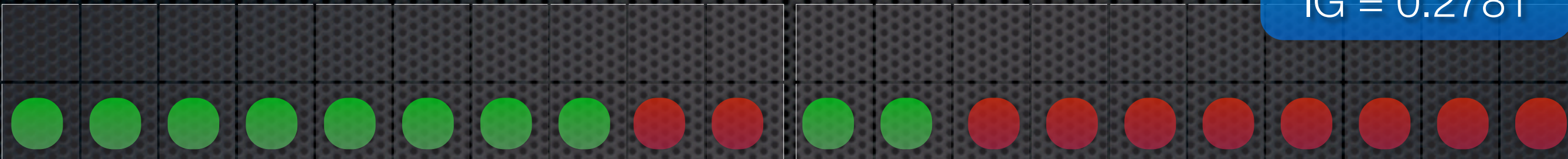


How does it look?

IG = 0.2781



IG = 0.2781



How does it look?

IG = 0.2781

P_1

P_1



IG = 0.2364

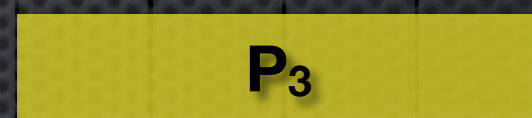
P_2

P_2



IG = 0.1678

P_3



How does it look?

IG = 0.2781

P_1

P_1



IG = 0.2364

P_2

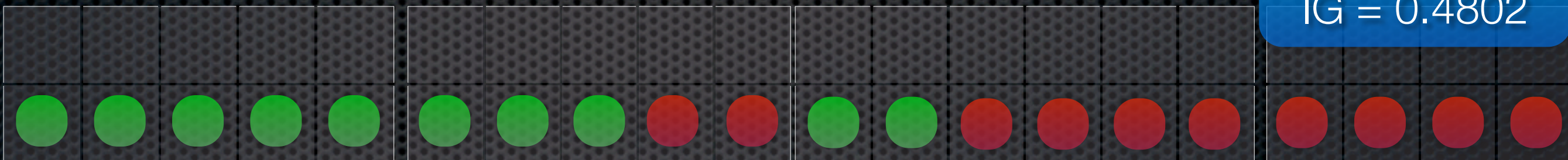
P_2

IG = 0.1678

P_3



IG = 0.4802



How does it look?

IG = 0.2781

P₁

P₁



IG = 0.2364

P₂

P₂

IG = 0.1678

P₃



IG = 0.4169

P₄

P₅

IG = 0.9235



How does it look?

IG = 0.2781

P₁

P₁



IG = 0.2364

P₂

P₂

IG = 0.1678

P₃

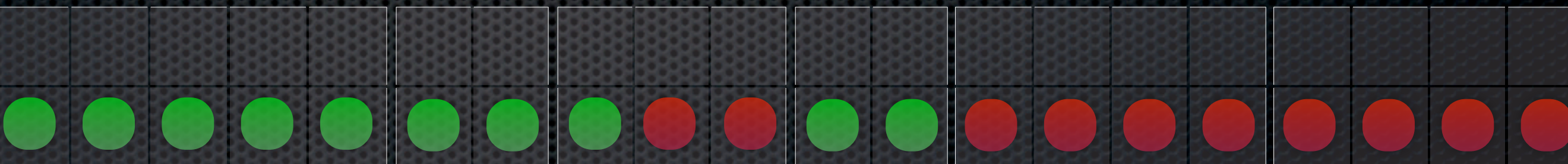


IG = 0.4169

P₄

P₅

IG = 0.9235



How does it look?

IG = 0.2781

P₁

P₁



IG = 0.2364

P₂

P₂

IG = 0.1678

P₃



IG = 0.4169

P₄

P₅

IG = 0.9235



IG = 0.8614



Pros and Cons

Reuses data unless purified

- Gradual refinement of description possible
- Over-fitting possible

Gradually smaller subsets

- Allows parallelization
- Harder cases, fewer candidates

Local measure optimization

- Less reliable evaluation individual patterns
- Many patterns, can be (partially) redundant

Partition refinement only locally

- Discards information about pattern effects
- Increases uncertainty about contribution single pattern

Single patterns do not have to be overly accurate

fCork

Measure: Correspondences

Optimization: Globally

Partition refinement: Globally, implicit

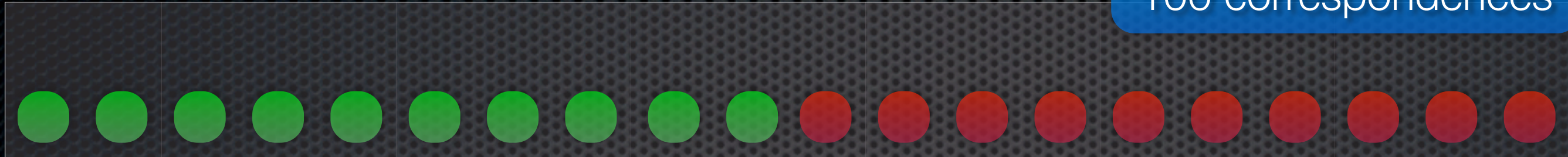
Mine pattern reducing correspondences best

Remove “pure” data points

Re-iterate

How does it look?

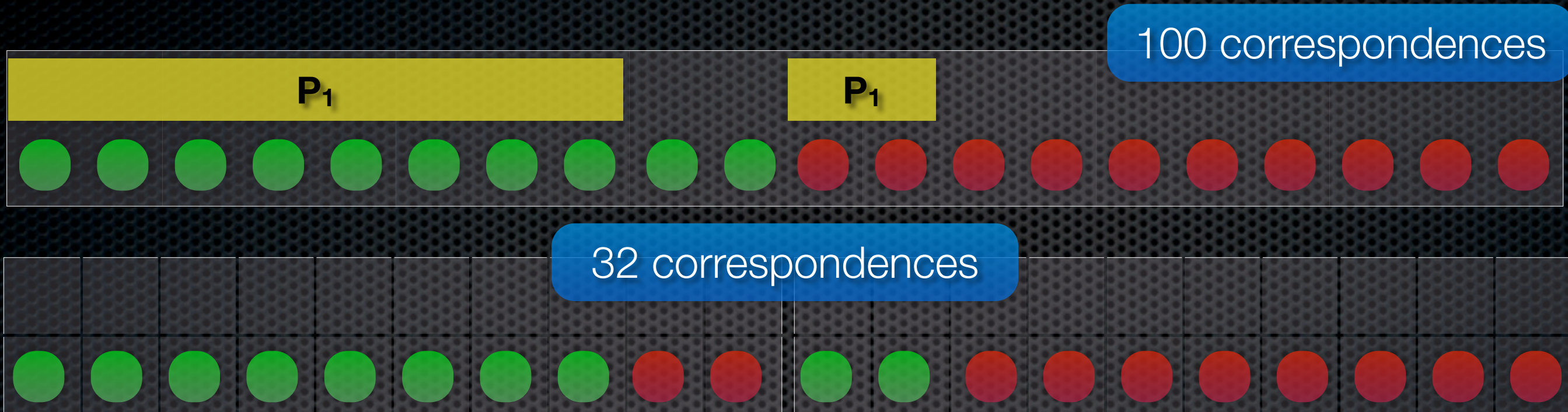
100 correspondences



How does it look?



How does it look?

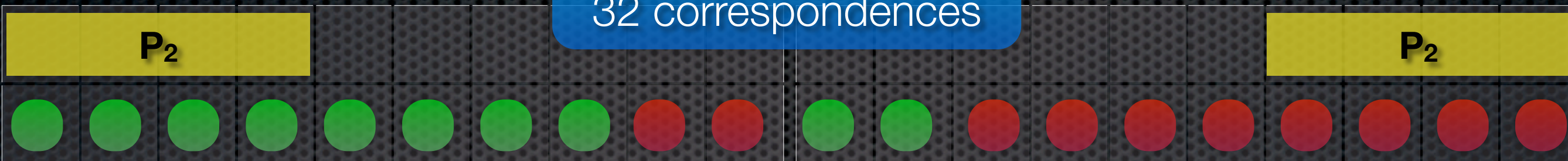


How does it look?

100 correspondences



32 correspondences



How does it look?

100 correspondences

P_1

P_1

32 correspondences

P_2

P_2

12 correspondences

How does it look?

100 correspondences

P_1

P_1

P_2

P_2

32 correspondences

12 correspondences

How does it look?

100 correspondences

P_1

P_1

P_2

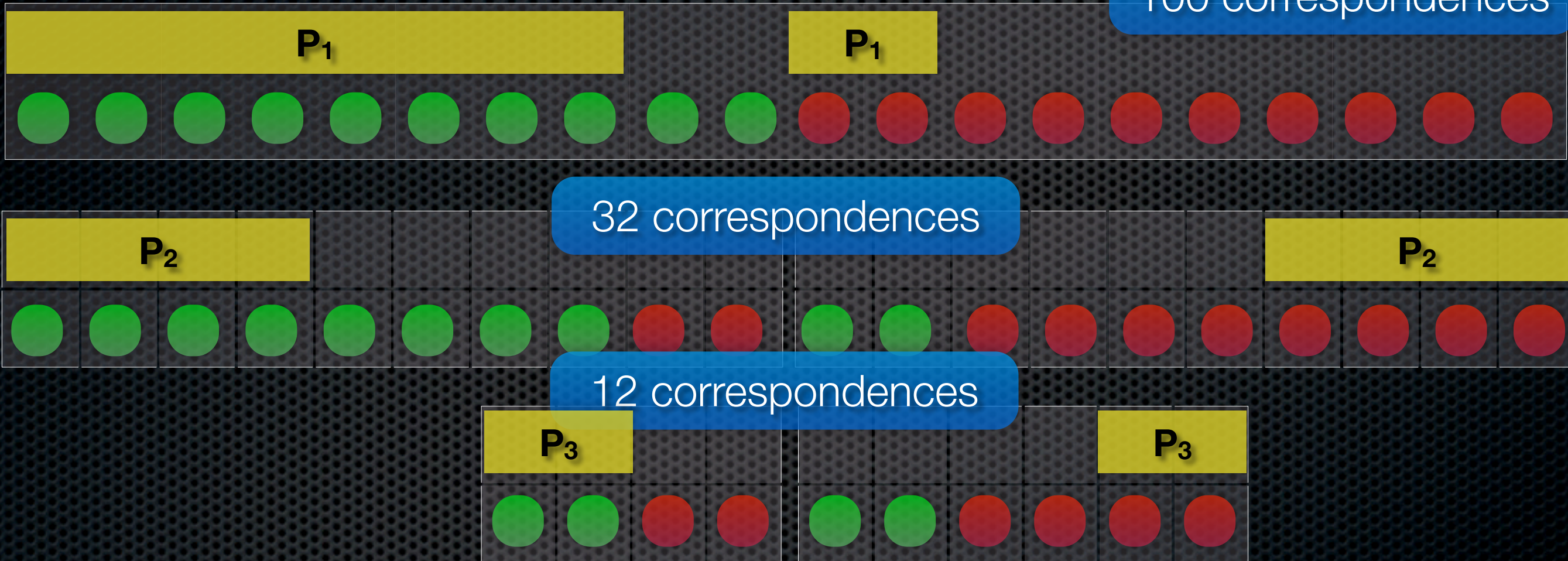
P_2

32 correspondences

12 correspondences

P_3

P_3



How does it look?

100 correspondences

P_1

P_1

P_2

P_2

32 correspondences

12 correspondences

P_3

P_3

4 correspondences

How does it look?

100 correspondences

P_1

P_1

32 correspondences

P_2

P_2

12 correspondences

P_3

P_3

4 correspondences

How does it look?

100 correspondences

P_1

P_1

32 correspondences

P_2

P_2

12 correspondences

P_3

P_3

4 correspondences

P_4

0 correspondences

Pros and Cons

WYSIWYG

- ✦ Global optimization allows concrete evaluation of pattern contribution
- ✦ Due to submodularity

Fewer data in later runs

- ✦ Harder cases, less candidates

Global partition refinement

- ✦ Fewer patterns

Slower for individual patterns

- ✦ Due to global evaluation

Correspondences \neq correspondences

6 correspondences



6 correspondences



ReMine

Let's build a hybrid!
(recent work)

Measure: Information Gain

Optimization: Locally (from DTM)

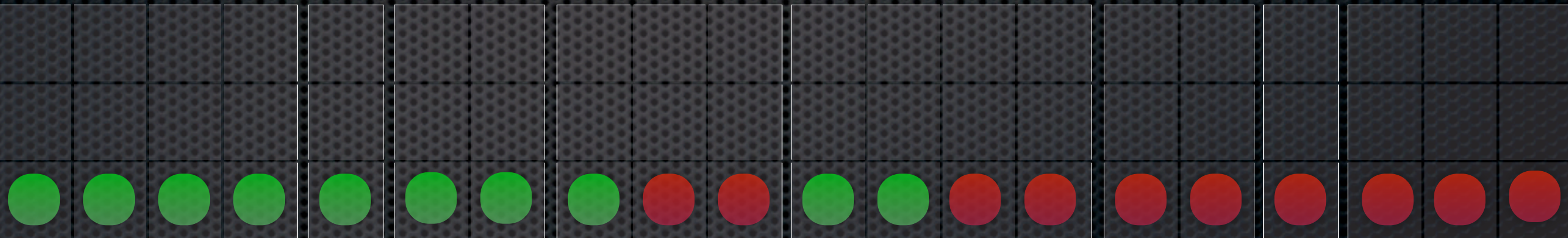
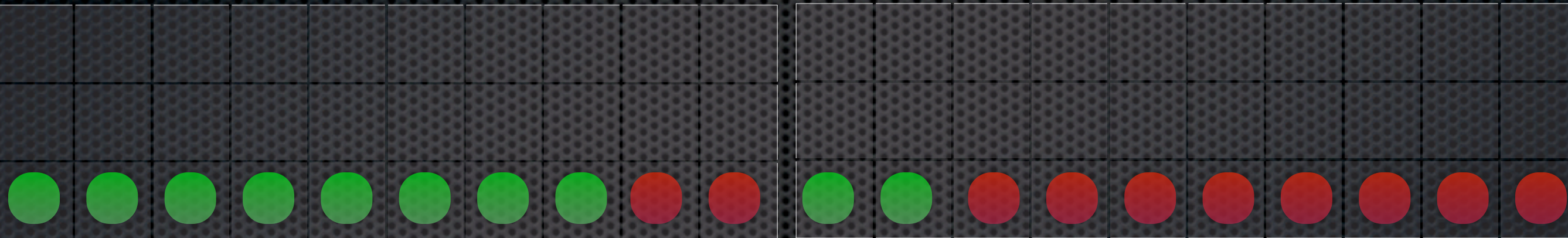
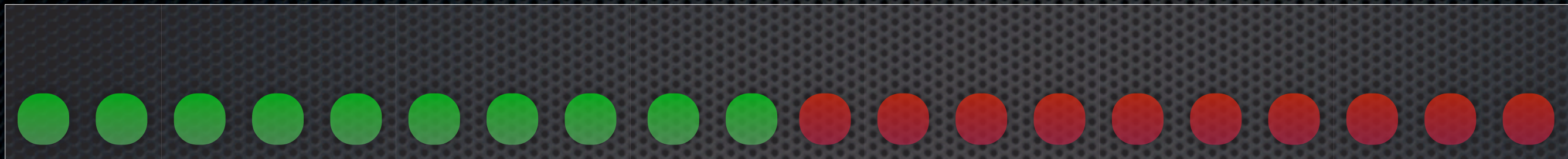
Partition refinement: Globally (from fCork), explicit (from DTM)

Mine pattern maximizing InfoGain

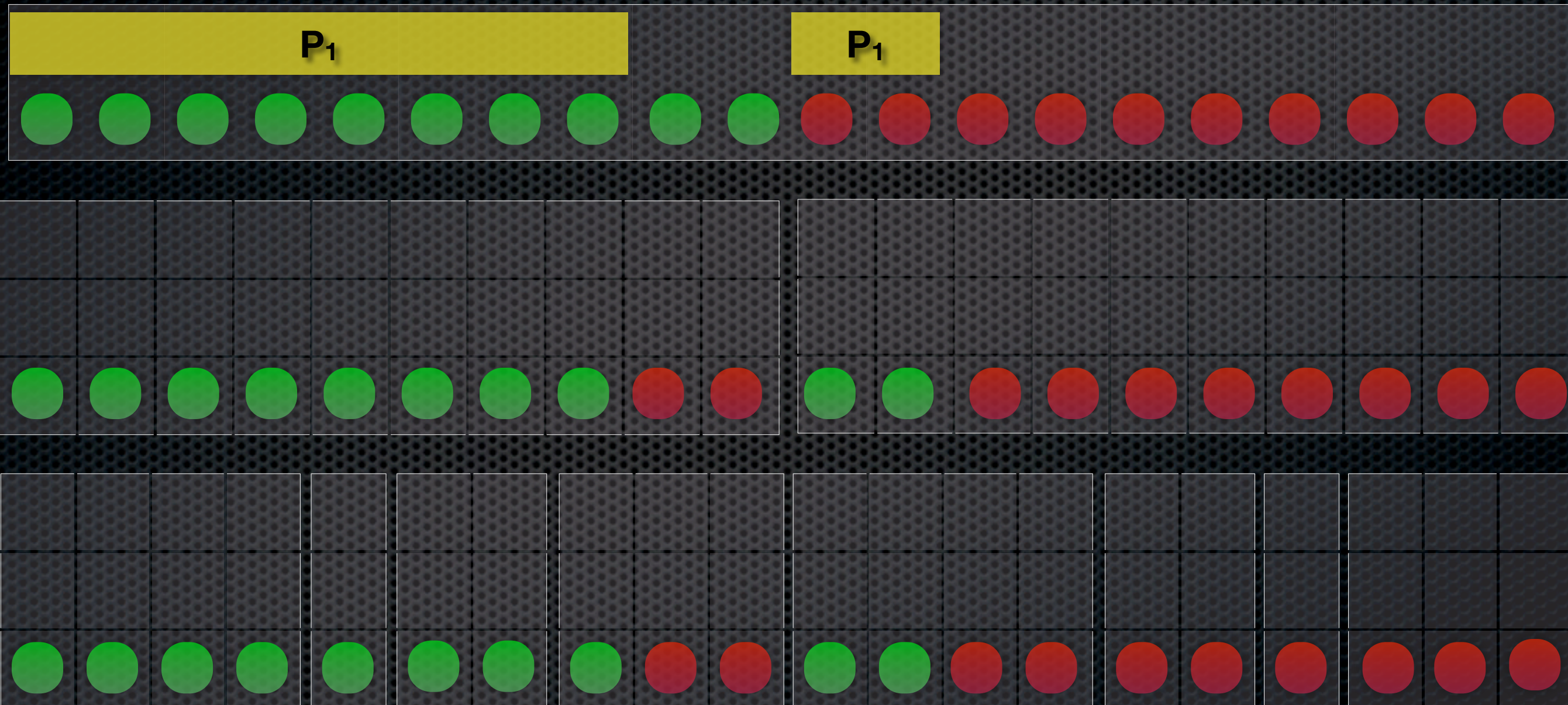
Partition **all** data using **all** patterns so far

Reiterate on subsets

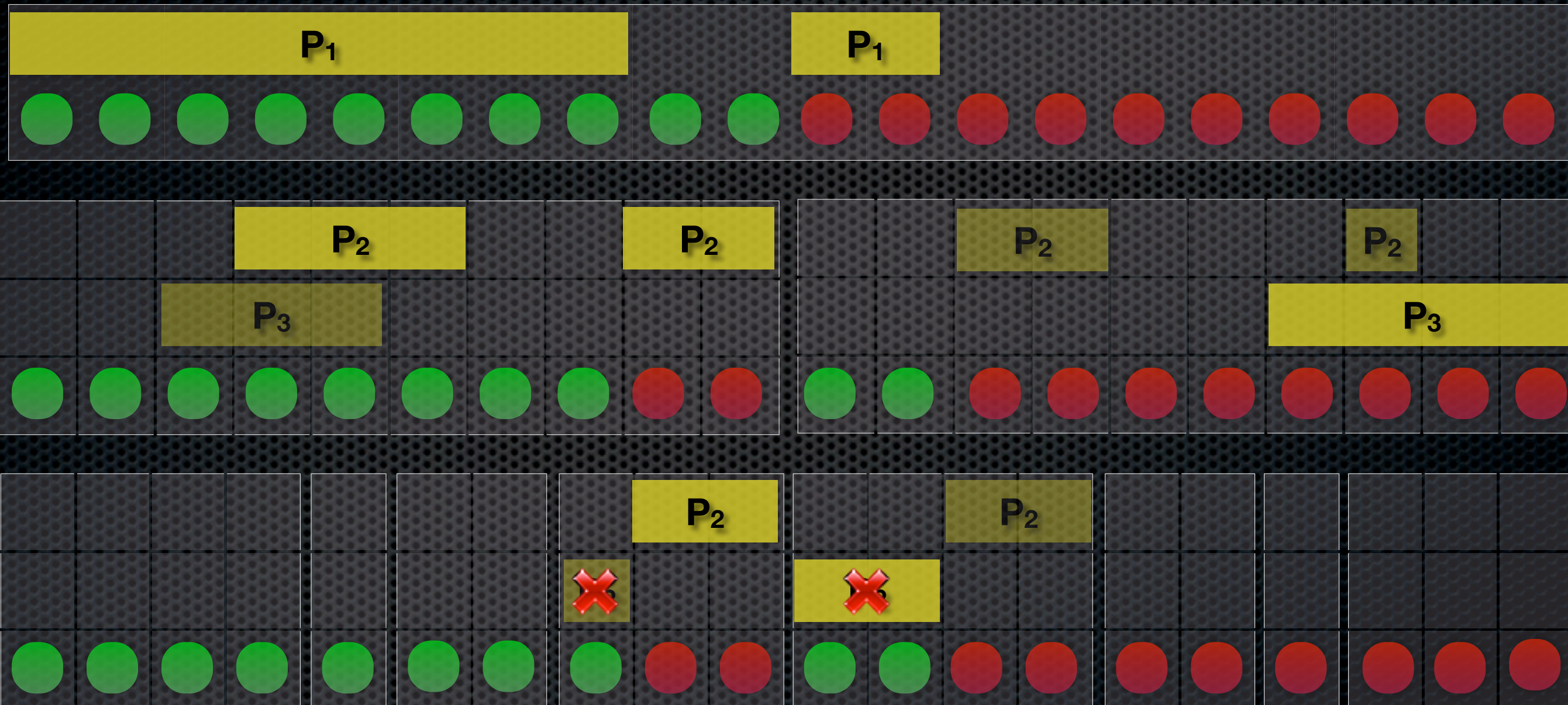
How does it look?



How does it look?



How does it look?



Pros and Cons

Global partition refinement

- More reliable pattern evaluation
- Fewer patterns than DTM, less redundancy

Quickly small subsets

- Faster than either DTM or fCork

Reuses data unless purified

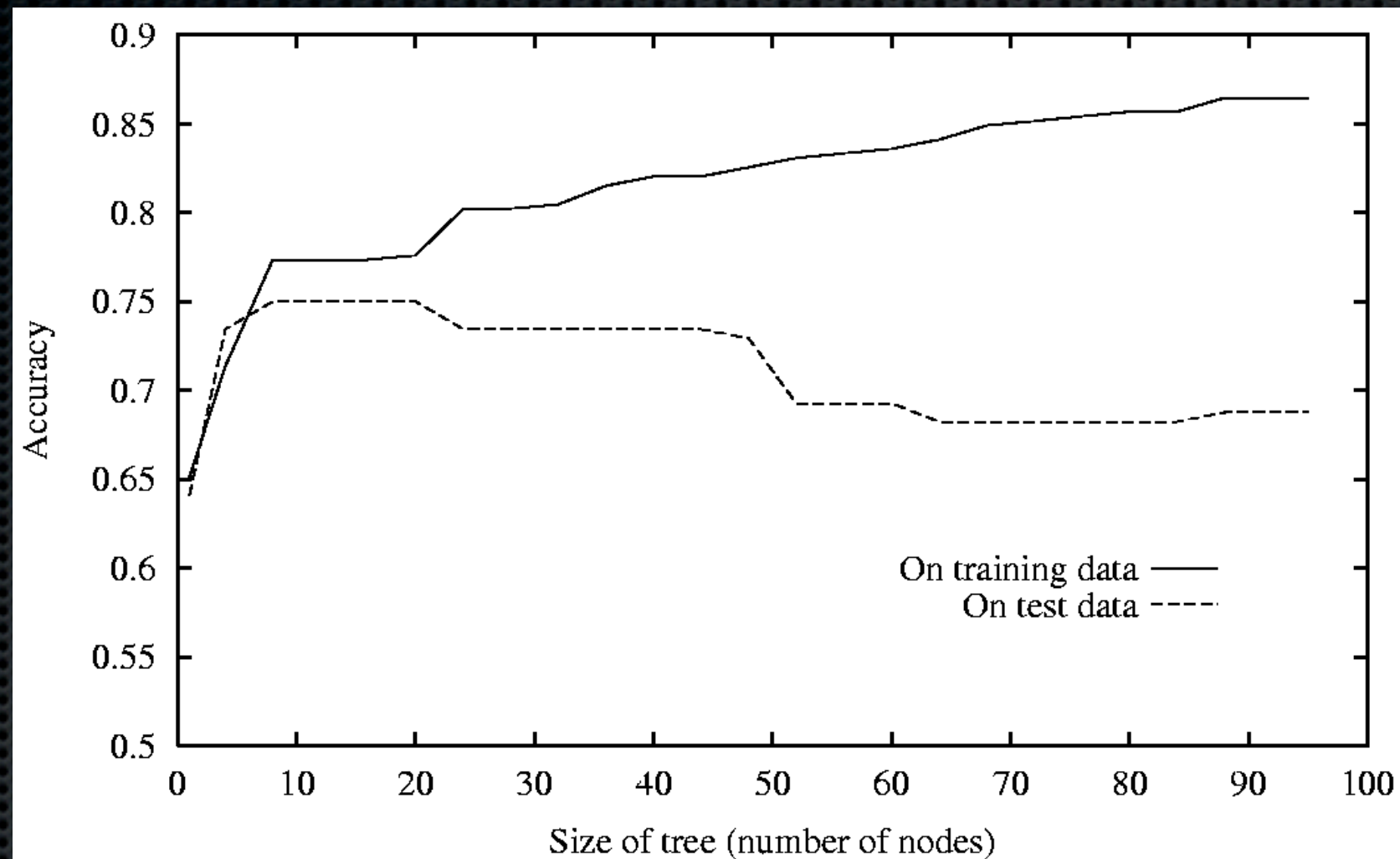
Local measure optimization

Over-fitting *seems* to occur

Loses *some* parallelization capability

- Due to waiting period for all patterns per level

One slide w.r.t over-fitting



Goal **is** effective set w.r.t. target

- I.e. good classification behavior

Fine-tuning patterns to split small subsets can capture noise

- DTM more redundancy, more features, slightly better AUC

Another slide about feature selection

Remember:

- Alleviating the effect of the curse of dimensionality
- Enhancing generalization capability
- Speeding up learning process
- Improving model interpretability

From Wikipedia's entry on "feature selection"

Between "wrapper"
and "filter"
Forward selection

Discussed techniques analogous to subset selection

- Known problem of over-fitting, sophisticated alternatives
- (Cross-)validation possible solution

Others exist

- Feature ranking (top- k mining - earlier work)

Thank you for your attention

Questions?